









75 YEARS OF EXPERIENCE, A DRIVING FORCE,

DESIGNED FOR THE FOTORI

TABARELLI







T308E ELECTRIC MATERIAL HANDLER



Pure energy by your side

Mode 1 > Power saving

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When this function is enabled, the material handling machine is set to a low rpm value to consume as little energy as possible. Therefore, its movements will be slower but more accurate.

The power saving mode is suitable for belt loading, hopper filling or mid-air loading. In this way, the battery life will be extended as far as possible.

Mode 2 > Balanced consumption

When this function is enabled, the material handler's energy consumption is optimised and all the movements, from travel to boom operation, are balanced. In this mode, the working speed is enough to carry out all the intended operations, from truck loading to ground sorting and walking floor loading. Mode 2 means maximum efficiency.

Mode 3 > High performance

When this function is enabled, the material handler is set to max. Power; the hydraulic system and the batteries provide the maximum possible yield disregarding the consumption, while ensuring at the same time the required power and speed. Mode 3 sets the material handler's performance to 100% of its capacity.

OPERATION IN 3 WORKING MODES: SLOW AND PRECISE, MEDIUM SPEED WITH BALANCED

- CONSUMPTION,

→SWIFT, HIGH PERFORMANCE.

More than **75** years of experience in the design and manufacture of wheeled material handlers for the collection and handling of ferrous scrap, metals and industrial waste is the best guarantee of a proven historical reliability.

All our material handlers have been designed and manufactured to ensure: great ease of use, low maintenance and high production performance.



HIGH EFFICIENCY BY YOUR SIDE

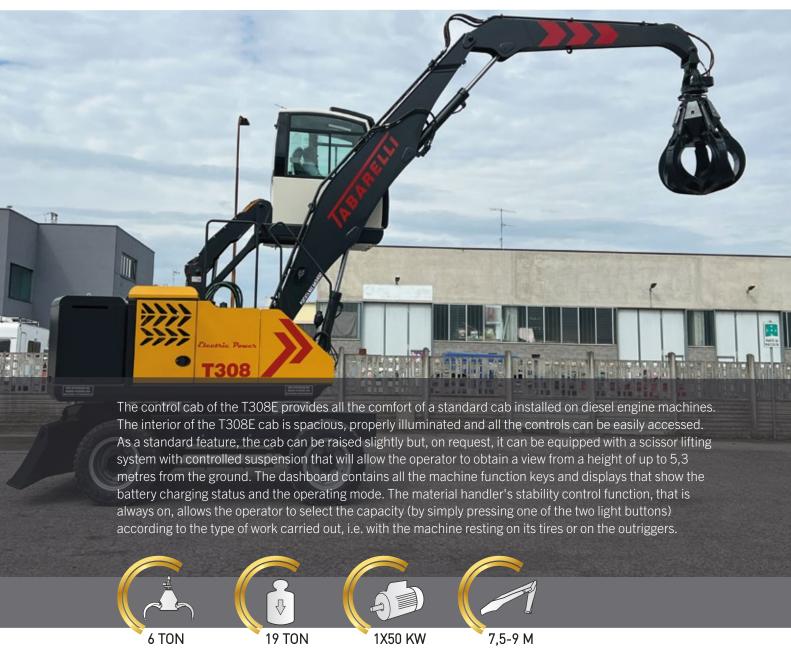
→POWER ENERGY

High driving charge

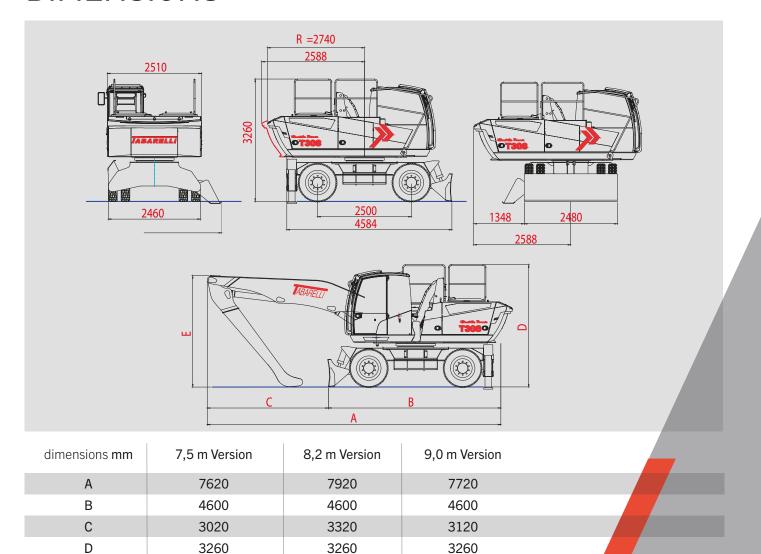
The T308E material handler is powered by 2 batteries housed in special compartments placed at the back of the swing drive that acts as a counterweight. The 960Ah/80V batteries are connected in parallel and are equipped with voltage reducers for the auxiliary circuits.

Two electronic Inverters control the motor that drives the main hydraulic pump and the auxiliary pump. Two high-frequency electronic battery chargers included, with high charging efficiency.





DIMENSIONS



3285

EQUIPMENT

> STANDARD

- > Radio with loudspeaker
- > 5 LED lights
- > Front blade
- > 4-wheel drive
- > 2-speed gearbox
- > Electric steering system
- > Super-elastic solid tires
- > Intermediate rubber rings
- > Two-pieces boom with secondary one monolithic, total length 7,5 m

2770

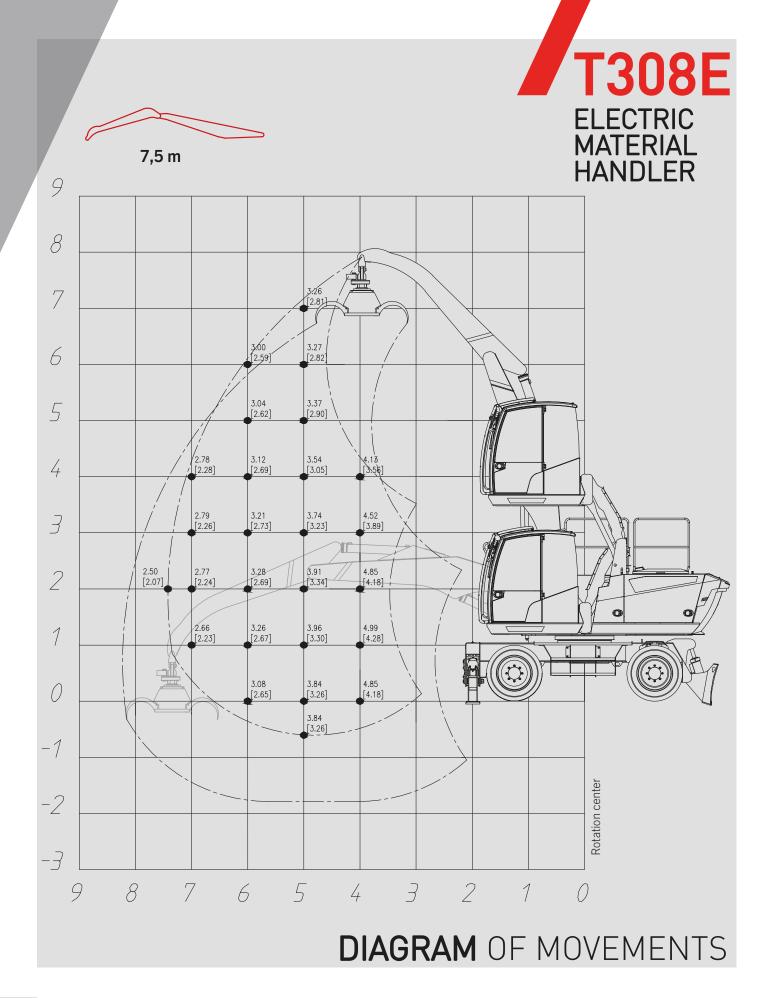
> Hydraulic lifting cab

< OPTIONAL

- < Rear outriggers
- < Pantograph lifting system.

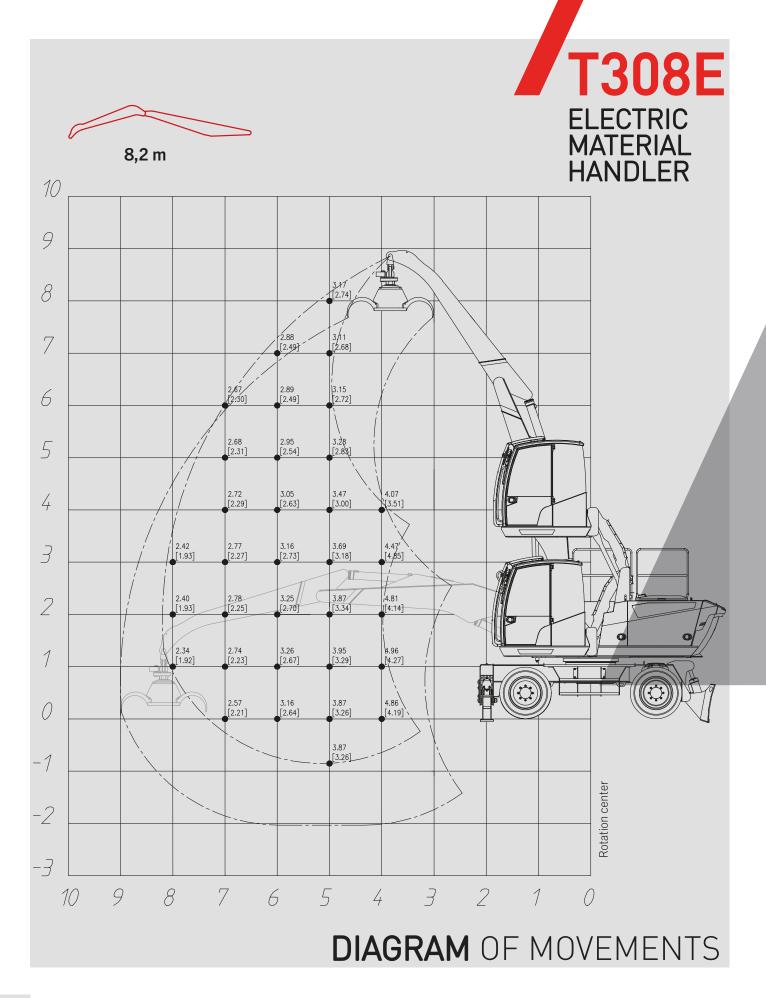
2980

- < Two- pieces boom with secondary one monolithic, total length 8,2 m
- < Two- pieces boom with secondary one monolithic, total length
- < Boom with hydraulic extension total length 7.5 m
- < Air conditioning with air-prefiltering



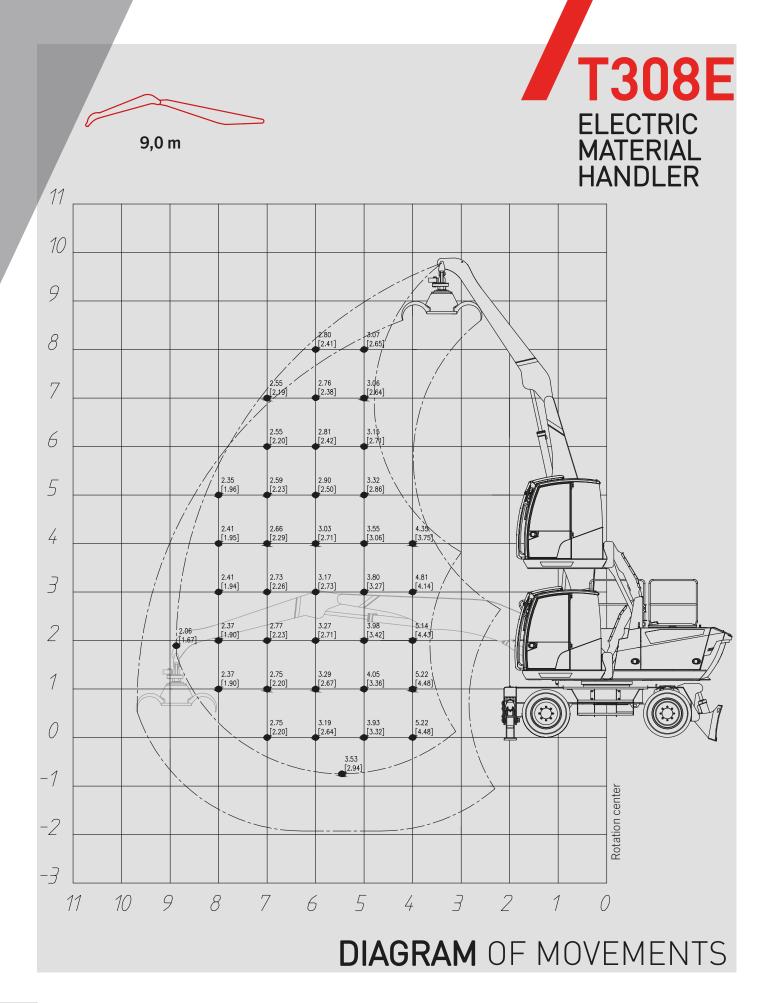
All load values are specified in tonnes (T) and apply at the end of the half-boom, without any gripping device installed, on firm, level ground. The values indicated correspond to 75% of the tipping load or 87% of the hydraulic lifting force, according to ISO 10567. The load ratings in brackets [], with a locked swing axle, refer to a stabilisation set-up on tyres (with stabilisers raised) and 360° turret rotation.

NOTE: Data and weights are indicative and not binding: Tabarelli reserves the right to make any modifications it deems appropriate.



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TECHNICAL SPECIFICATIONS

MOTOR

Type Electric motor with alternating current power of 1X50kW

Batteries 2x960Ah - 80V

Motor speed (RPM) selector switch with 4 operating modes

adjustment

HYDRAULIC SYSTEM

Main pump variable displacement axial-piston pump

Delivery rate 180 l/min **Max operating pressure** 280 Bar

Adjustment Electro-hydraulic controls

Heat exchanger water/oil element side by side with by-pass valve

Filtering partial return to the tank

Hydraulic tank capacity 2151

SLEWING DRIVE

Engine with axial pistons

Gearbox The gearbox is comprised of two stages of planetary systems

Slewing ring double-row ball bearing slewing ring, made of special steel with hardened inner gear

Slewing speed 0-8 rpm

CAB

Operator's Cab spacious and comfortable, heated, soundproofed, with hydraulic pantograph lifting system.

Working position with a view up to 4,3 meters height from the ground.

Front grille guard and n. 5 LED work lights

Drive Hydraulic drive with steering wheel or with electric control

Seat "GRAMMER "gran comfort" with 6 settings and weight-adjustable suspension

Dashboard Wide colour display with text and graphic symbols to control the main machine functions,

alarms and data.

Main cross-motion multifunction armrest with cross joystick

servo-controls

Shift 2-levers pedal

Auxiliary Movements Control electric-hydraulic

UNDERCARRIAGE

Shifting hydraulic axial piston motor with starting and braking control valve

Drive 2-speed transmission with electro-hydraulic control

Axles Four-wheel drive with strong steering axles and planetary gearbox in the hubs. Steering and

oscillating front axle with integrated hydraulic locking

Rims 6.50/20 with 8 holes

Tires 8 super-elastic solid tyres 8.25/20

Brake parking brake

Speed Stage I: 0-3 km/h | Stage II: 0-12 km/h

Outriggers 2-point, rear

Blade 1-front blade with stabilizer function

BOOM

Structure made of high-strength steel, in 2 elements with secondary monolithic

Length from 7.5 to 9 meters optional **Bushings and pins** made of special steel for concrete

Cylinders single cylinder on 1st and 2nd boom with hydraulic brake

WEIGHT about 19 ton in working order

RECOMMENDED Grab for waste model RR560 with 5 blades

EQUIPMENT Grab for scrap model RV320 with 6 blades

SOUND LEVEL NOISE REDUCTION (Dir 2000/14/CE - 2005/88/CE)

Sound pressure level at driving position LpA 77 dB (A)

MOVEMENT METER MACHINERY DIRECTIVE (Dir 2006/42/CE)

Electronic monitoring device for the stability of the machine according to

the loads moved and their position with warning of danger by means of acoustic and light

signals, blocking of movements upon reaching of stability limits.



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